Real Second-degree Binary Polynomial Equations #79 of Gottschalk's Gestalts

A Series Illustrating Innovative Forms of the Organization & Exposition of Mathematics by Walter Gottschalk

Infinite Vistas Press PVD RI 2002

GG79-1 (25)

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 \Box the general real second - degree polynomial equation in the two real number variables x and y in canonical form

$$=_{df}$$

$$Ax^{2} + Bxy + Cy^{2} + Dx + Ey + F = 0 \quad (*)$$
wh
$$A, B, C, D, E, F \in real nr$$
st
$$A \neq 0 \lor B \neq 0 \lor C \neq 0$$

 \Box if the real number variables x and y

are interpreted as coordinates,

abscissa and ordinate,

of a point P in the euclidean plane provided with

a rectangular coordinate system with x - axis and y - axis, then

the graph of (*)

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= the set of all points P(x, y) satisfying (*)
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is a conic section

or two parallel straight lines

or the empty set;

the graph classification theorem below

spells out this fact in detail

according to the nature of the coefficients of (*)

 $\Box a conic section$ =_{df} a plane section of a two - nappe right circular cone in euclidean 3 - space

□ a conic section is one of the following curves:

an ellipse = a proper ellipse
which has
two distinct foci & two distinct directrices
& unequal positive semiaxes
& positive eccentricity < 1
& a center of symmetry
& two axes of symmetry
and
which is
a convex simple closed curve

• a hyperbola = a proper hyperbola which has

two distinct foci & two distinct directrices

& positive semiaxes

& eccentricity > 1

& a pair of intersecting straight - line asymptotes

& a center of symmetry

& two axes of symmetry

& two branches

which are convex simple open

unbounded congruent arcs

• a parabola = a proper parabola

which has

one focus & one directrix with focus ∉ directrix

& positive latus rectum

& eccentricity = 1

& no center of symmetry

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& one axis of symmetry
```

and

which is

a convex simple open unbounded curve,

a circle = a proper circle
which has
a positive radius
(a circle may be considered to be
a degenerate / limiting form
of an ellipse
with coincident foci
& equal semiaxes
& eccentricity = 0)

• a point

(a point may be considered to be a degenerate / limting form of an ellipse with zero semiaxes or

of a circle with zero radius)

one straight line
(may be considered to be a degenerate / limiting form of a parabola
with zero curvature)

two intersecting straight lines
(may be considered to be a degenerate / limiting form of a hyperbola
which coincides with its asymptotes)

conversely,
any such curve is congruent to
a plane section of a right circular cone

□ strictly speaking two parallel straight lines and the empty set are not conic sections; but they are plane sections of the degenerate / limiting form of a right circular cone when the vertex recedes to infinity viz a right circular cylinder

a plane section of a right circular cylinder is one of the following curves:
empty set,
a single line,
two parallel lines,
a circle,
an ellipse;
conversely,
any such curve is congruent to
a plane section of a right circular cylinder

• a single straight line and

a pair of parallel straight lines may each be considered to be a degenerate / limiting form of an ellipse when the foci go to infinity in the opposite directions \Box the following functions d, q, t, s of the coefficients of (*) are called invariants of (*) because their values remain unchanged when the coordinate axes are translated and rotated to obtain a new equation; when (*) is multiplied by a nonzero real number k, the new equation has the same graph as the original equation but the original d is multiplied by k^3 , q is multiplied by k^2 , t is multiplied by k, s remains unchanged

• the discriminant of (*)

 $=_{dn} d$

$$=_{df} \begin{vmatrix} A & \frac{B}{2} & \frac{D}{2} \\ \frac{B}{2} & C & \frac{E}{2} \\ \frac{D}{2} & \frac{E}{2} & F \end{vmatrix}$$

• the quadratic discriminant of (*)

 $=_{dn} q$

$$=_{df} \begin{vmatrix} A & \frac{B}{2} \\ \frac{B}{2} & C \end{vmatrix}$$

• the quadratic trace of (*)

 $=_{dn} t$ $=_{df} A + C$

• the sign invariant of (*)

=_{dn} s

$$=_{df} sgn \left(\begin{vmatrix} A & \frac{D}{2} \\ \frac{D}{2} & F \end{vmatrix} + \begin{vmatrix} C & \frac{E}{2} \\ \frac{E}{2} & F \end{vmatrix} \right)$$

• note that

the three second - order determinants appearing in the definitions of q & s are the minors of the diagonal entries of the third - order determinant appearing in the definition of d

•
$$t^2 = 4q \iff A = C \& B = 0$$

The Graph Classification Theorem
 for Real Second - degree Polynomial Equations
 in Two Variables

the graphs of the equations in the form (*) are described in the following six exclusive & exhaustive cases: Δ case I. d \neq 0 & q > 0

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• subcase I<sub>1</sub>. sgnd \neq sgnt & 4q \neq t<sup>2</sup>

\Rightarrow

graph = an ellipse
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• subcase I<sub>2</sub>. sgnd \neq sgnt & 4q = t<sup>2</sup>

\Rightarrow

graph = a circle
```

```
• subcase I<sub>3</sub>. sgnd = sgnt

\Rightarrow

graph = \emptyset
```

 $\Delta \text{ case II. } d \neq 0 \& q < 0$ \Rightarrow

graph = a hyperbola

 $\Delta \text{ case III. } d \neq 0 \& q = 0 \\ \Rightarrow$

graph = a parabola

 $\Delta \text{ case IV. } d = 0 \& q > 0$ \Rightarrow graph = one point

 Δ case V. d = 0 & q < 0

\Rightarrow

graph = the union of

two distinct intersecting straight lines

```
\Delta \operatorname{case} \operatorname{VI.} d = 0 & q = 0

• subcase \operatorname{VI}_1 \cdot s > 0

\Rightarrow

graph = \emptyset

• subcase \operatorname{VI}_2 \cdot s < 0

\Rightarrow

graph = the union of

two distinct parallel straight lines
```

• subcase
$$VI_3$$
. s = 0

 \Rightarrow

graph = one straight line