

Angles on Angles

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of the Organization & Exposition
of Mathematics
by Walter Gottschalk

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GG16-2

□ the notion of plane angle

△ we recognize three kinds of plane angles:

sectorial angles

rotary angles

radial angles

- plane angle as infinite circular sector

= plane angle as sector

= plane angle as sectorial angle

= sectorial plane angle

= sectorial angle

- plane angle as rotation of a ray about its vertex

= plane angle as rotation

= plane angle as rotary angle

= rotary plane angle

= rotary angle

- plane angle as union of rays in the plane

with a common vertex

= plane angle as ray-union

= plane angle as radial angle

= radial plane angle

= radial angle

△ the notion of radial angle

generalizes the notion of sectorial angle;
a sectorial angle is a special kind of radial angle;
radial angles that are not sectorial angles
are not ordinarily encountered until after
calculus level math courses;
but it is the notion of radial angle
that extends easily to higher dimensions
and in particular to solid (= three-dimensional) angles

△ as with all geometric objects

a basic question arises as to
how to measure the magnitude
of these various kinds of angle

□ pictures of sectorial & rotary angles

- to draw a picture of a sectorial angle
draw the sides from the vertex
and draw a circle arc centered at the vertex
that lies between the sides
and within the angle;
to indicate another sectorial angle
on the same diagram
draw two such circle arcs close together
or mark a circle arc
with a short tick (crosspiece)
in the middle of the arc;
increase numbers of arcs and of ticks on arcs
to indicate more sectorial angles

- to identify a right sectorial angle by sight
complete a small square in the corner

- to draw a picture of a rotary angle
draw the sides from the vertex
and draw an expanding/contracting
counterclockwise/clockwise pointed spiraling arc
from the initial side to the terminal side
to indicate the direction and the numerical value
of the rotation

□ visualizing a radial angle

- here is a way of thinking of a radial angle;
a radial angle is determined by
a point in the plane,
called the vertex V ,
and
any nonempty set in the plane,
called the directrix D ;
take the union A of all rays (= half-lines) from V
passing thru a point in D ;
the set A is a radial angle;
it is said that
the directrix D subtends the angle A
from the vertex V
and
the angle A is subtended by the directrix D
from the vertex V ;
if D lies on the unit circle centered at V ,
then the numerical 'length' of D
is taken to be the measure in radians
of the radial angle A

□ the notion of spacial angle

△ we recognize two kinds of spacial angles:

dihedral angles

solid angles

- a dihedral angle,
visualized as two pages in a book
with both pages stationary
or one page stationary and the other turning,
can be thought of
as extending the two notions of
sectorial plane angle
and
rotary plane angle
to spacial angles;
a perpendicular plane section of a dihedral angle
produces
one of these two kinds of plane angle
whose measure is taken to be
the measure of the dihedral angle

- a solid angle
is defined to be
a union of rays in space
with a common vertex;
a solid angle is a ray-union;
a solid angle is a kind of radial (= made up of rays) angle
and indeed extends the notion of radial plane angle
to spacial angles

- a sectorial dihedral angle
is a special kind of a solid angle
but the measure
of the plane section of the dihedral angle
differs from the measure as solid angle

□ visualizing a solid angle

- here is a way of thinking of a solid angle;
a solid angle is determined by
a point in space,
called the vertex V ,
and
any nonempty set in space,
called the directrix D ;
take the union A of all rays (=half-lines) from V
passing thru a point in D ;
the set A is a solid angle;
it is said that
the directrix D subtends the angle A
from the vertex V
and
the angle A is subtended by the directrix D
from the vertex V ;
if D lies on the unit sphere centered at V ,
then the numerical 'area' of D
is taken to be the measure in steradians
of the solid angle A

□ units of angle measure

- for sectorial or rotary plane angles
there are two primary units of measure
that concern us

viz

the dimensionless unit of plane angle measure called
degree

(with subunits called 'minute' and 'second')

and

the dimensionless unit of plane angle measure called
radian

- for solid angles

there is one primary unit of measure
that concerns us

viz

the dimensionless unit of solid angle measure called
steradian

- both the radian and the steradian are
supplementary (because dimensionless) SI units

ie

units in the

Système International d'Unités (French)

= International System of Units

which is the standard system of scientific units
used worldwide

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□ the measure in degrees = the degree measure
of sectorial angles

• by definition

one round angle

$$= 360 \text{ degrees} = 360 \text{ deg} = 360^{\text{deg}} = 360^{\circ}$$

$$1 \text{ degree} = 1^{\circ} = 60 \text{ minutes} = 60 \text{ min} = 60^{\text{min}} = 60'$$

$$1 \text{ minute} = 1' = 60 \text{ seconds} = 60 \text{ sec} = 60^{\text{sec}} = 60''$$

$$1 \text{ second} = 1'' = 1 \text{ sec} = 1^{\text{sec}}$$

□ a vanishing but useful notation

- given an angle A

then its measure

in whatever unit that would be understood

may be denoted by

$\text{meas } A$ or simply mA ;

however

if no ambiguity can reasonably arise,

then the measure of A

may be denoted by A itself

□ classification & names of sectorial angles
characterized by degree measure

- A is a sectorial angle:

$$0^\circ \leq A \leq 360^\circ$$

- A is a zero angle:

$$A = 0^\circ$$

- A is an acute angle:

$$0^\circ < A < 90^\circ$$

- A is a right angle:

$$A = 90^\circ$$

- A is an obtuse angle:

$$90^\circ < A < 180^\circ$$

- A is a straight angle:

$$A = 180^\circ$$

- A is a reflex - obtuse angle:

$$180^\circ < A < 270^\circ$$

- A is a reflex - right angle:

$$A = 270^\circ$$

- A is a reflex - acute angle:

$$270^\circ < A < 360^\circ$$

- A is a round angle:

$$A = 360^\circ$$

note: once around a point
gives a round angle

- A is an oblique angle:

A is an acute angle

or

A is an obtuse angle

- A is a reflex - oblique angle:

A is a reflex - obtuse angle

or

A is a reflex - acute angle

- A is a flex angle:

$$0^\circ \leq A \leq 180^\circ$$

- A is a reflex angle:

$$180^\circ \leq A \leq 360^\circ$$

- A is a semisextile angle:

$$A = 30^\circ$$

- A is a semiright angle:

$$A = 45^\circ$$

- A is a sextile angle:

$$A = 60^\circ$$

- A is a trine angle:

$$A = 120^\circ$$

- A is a sesquirit angle:

$$A = 135^\circ$$

- A is a sesquicentral angle:

$$A = 150^\circ$$

- A is an n degree angle wh $n \in \mathbb{R}[0, 360]$:

$$A = n^\circ$$

• A is a quadrant one angle = A is a Q I angle
= A is in quadrant one = $A \in \text{Q I}$:

$$0^\circ \leq A \leq 90^\circ$$

• A is a quadrant two angle = A is a Q II angle
= A is in quadrant two = $A \in \text{Q II}$:

$$90^\circ \leq A \leq 180^\circ$$

• A is a quadrant three angle = A is a Q III angle
= A is in quadrant three = $A \in \text{Q III}$:

$$180^\circ \leq A \leq 270^\circ$$

• A is a quadrant four angle = A is a Q IV angle
= A is in quadrant four = $A \in \text{Q IV}$:

$$270^\circ \leq A \leq 360^\circ$$

• A is a quadrantal angle = A is a Q angle
= A is quadrantal = $A \in \text{Q}$:

$$A = 0^\circ \text{ or } 90^\circ \text{ or } 180^\circ \text{ or } 270^\circ \text{ or } 360^\circ$$

- A is an open quadrant N angle

and

A is in open quadrant N

provided that the corresponding strict inequalities hold,

and a small open circle may be placed above Q as $\overset{\circ}{Q}$

for the notation (here o stands for 'open');

to emphasize the earlier notion,

say that

A is a closed quadrant N angle

and

A is in closed quadrant N,

and place a horizontal bar above Q as \overline{Q}

for the notation

- A and B are complementary angles
- = A and B are complementary
- = A and B are complements (of each other)
- = A is complementary to B
- = A is the complement of B :

$$A + B = 90^\circ$$

- A and B are supplementary angles
- = A and B are supplementary
- = A and B are supplements (of each other)
- = A is supplementary to B
- = A is the supplement of B :

$$A + B = 180^\circ$$

- A and B are complementary angles
- = A and B are complementary
- = A and B are complements (of each other)
- = A is complementary to B
- = A is the complement of B :

$$A + B = 180^\circ$$

- A and B are supplementary angles
- = A and B are supplementary
- = A and B are supplements (of each other)
- = A is supplementary to B
- = A is the supplement of B :

$$A + B = 360^\circ$$

□ the measure in radians = the radian measure
of sectorial angles

• by definition

one round angle

$$= 2\pi \text{ radians} = 2\pi \text{ rad} = 2\pi^{\text{rad}} = 2\pi^{\text{r}}$$

$$1 \text{ radian} = 1 \text{ rad} = 1^{\text{rad}} = 1^{\text{r}}$$

□ an angle on angle measure:
degree measure vs radian measure;
numerical conversion from one measure to the other

- remember

$$360^\circ = \text{one round angle} = 2\pi^r$$

- start with

$$360^\circ = 2\pi^r$$

- now divide successively by
the $24 = 4 \times 3 \times 2$ factors of

$$360 = 2^3 \times 3^2 \times 5 \quad (\text{pf})$$

viz

1	360
2	180
3	120
4	90
5	72
6	60
8	45
9	40
10	36
12	30
15	24
18	20

to obtain the quotients

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$$360^\circ = 2\pi^r$$

$$1^\circ = \frac{\pi^r}{180}$$

$$180^\circ = \pi^r$$

$$2^\circ = \frac{\pi^r}{90}$$

$$120^\circ = \frac{2\pi^r}{3}$$

$$3^\circ = \frac{\pi^r}{60}$$

$$90^\circ = \frac{\pi^r}{2}$$

$$4^\circ = \frac{\pi^r}{45}$$

$$72^\circ = \frac{2\pi^r}{5}$$

$$5^\circ = \frac{\pi^r}{36}$$

$$60^\circ = \frac{\pi^r}{3}$$

$$6^\circ = \frac{\pi^r}{30}$$

$$45^\circ = \frac{\pi^r}{4}$$

$$8^\circ = \frac{2\pi^r}{45}$$

$$40^\circ = \frac{2\pi^r}{9}$$

$$9^\circ = \frac{\pi^r}{20}$$

$$36^\circ = \frac{\pi^r}{5}$$

$$10^\circ = \frac{\pi^r}{18}$$

$$30^\circ = \frac{\pi^r}{6}$$

$$12^\circ = \frac{\pi^r}{15}$$

$$24^\circ = \frac{2\pi^r}{15}$$

$$15^\circ = \frac{\pi^r}{12}$$

$$20^\circ = \frac{\pi^r}{9}$$

$$18^\circ = \frac{\pi^r}{10}$$

- also note

$$1^\circ = \frac{\pi}{180} \text{ r} \approx 0.01745 \text{ r}$$

$$1 \text{ r} = \frac{180^\circ}{\pi} \approx 57.29578^\circ \approx 57^\circ 17' 45''$$

which contains

a remarkable accidental (?) simultaneous occurrence of 1745
in the two approximations

- now 1745 was a very good year:
it was the year the Leyden jar was invented

□ measure of circular = circle arcs

- by definition

the measure of a circular = circle arc

is

the measure in

degrees/minutes/seconds/radians/whatever

of the central angle, a sectorial angle,

that has its vertex at the center of the arc

and

that subtends the given arc

- the notion of arc measure

is useful in

astronomy

geodesy

geography

meteorology

space navigation

terrestrial navigation

□ clockwise vs counterclockwise

△ the meaning of the words

- 'clockwise' & 'counterclockwise'

refer physically

to the two opposite directions of rotary motion
in a horizontal or vertical plane before us

- 'clockwise'

means literally

'in the manner of the clock'

ie

in the manner in which clockhands turn;

clockhands are designed to turn the way they do
because

that is the direction of motion

of the shadow of the gnomon on a sundial

in the northern hemisphere

(it's counterclockwise on a sundial

in the southern hemisphere

but their clocks still turn the same as northerners')

- 'counterclockwise'

means literally

'counter/contrary/opposed/opposite to clockwise'

ie

opposite to the manner in which clockhands turn

Δ meaning of positive & negative rotary directions

- for a physical plane:

the 'positive' rotary direction for/in/of the physical plane
= df the counterclockwise direction

&

the 'negative' rotary direction for/in/of the physical plane
= df the clockwise direction

- for a geometric plane

provided with

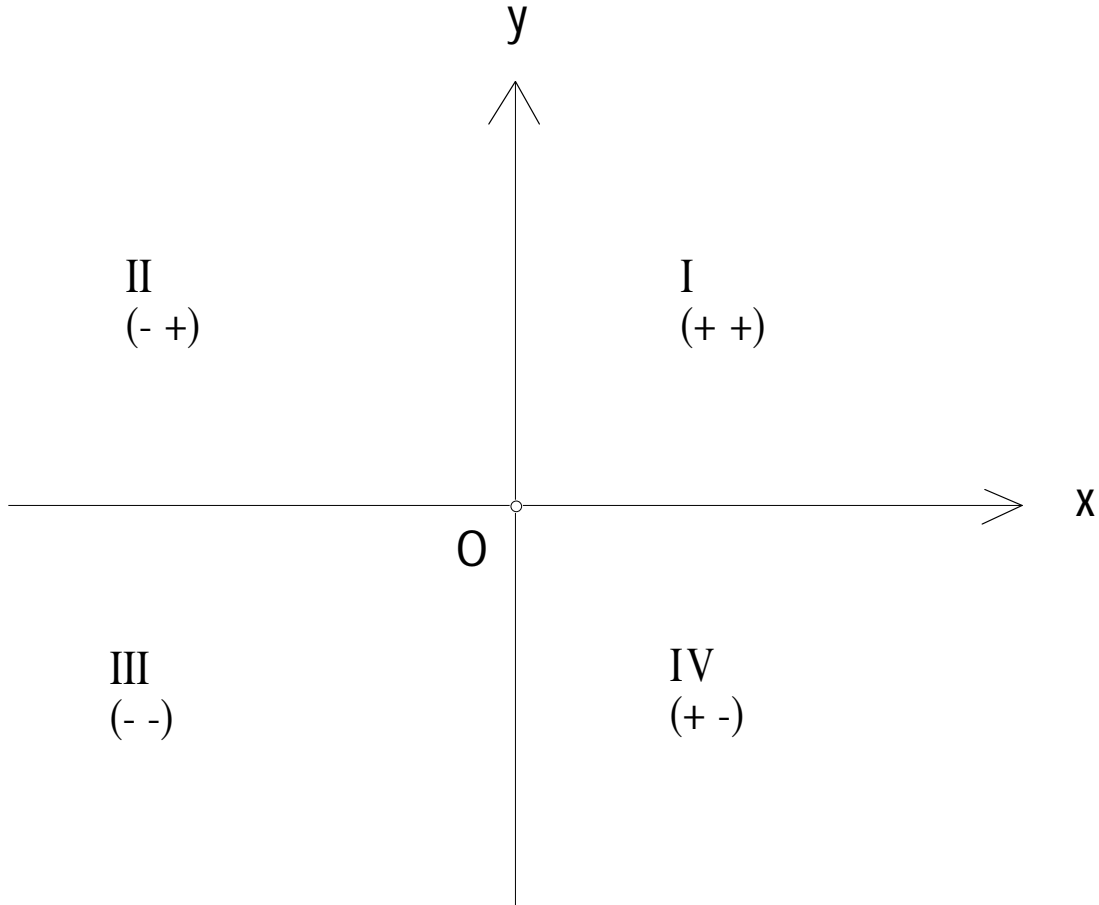
a rectangular (x, y) coordinate system:

the 'positive' rotary direction for/in/of the coordinate plane
= df from the positive x-axis to the positive y-axis
around the origin proceeding first thru quadrant one

&

the 'negative' rotary direction for/in/of the coordinate plane
= df from the positive y-axis to the positive x-axis
around the origin proceeding first thru quadrant one

Δ the two definitions of
'positive' & 'negative' rotary directions for
a physical plane
&
a coordinate plane
agree
when
the coordinate axes are taken to be
in the canonical/standard pictorial position
viz



Δ explaining the choice

- ¿ why should counterclockwise be chosen as positive ?
- 'counterclockwise' is equivalent to 'turning to the left'
- ¿ is there a built-in human bias for turning left rather than right ?
- it is possible that for the majority of people turning to the left is physiologically easier than turning to the right; i find this true when riding on a bicycle; i am right-handed
- oval racing courses for

bicycles

boats/ships

cars

dogs

humans on foot

horses

motorcycles

planes

all seem to be run counterclockwise

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□ the measure in degrees / radians
= the degree / radian measure
of rotary angles

- a rotary angle is defined to be positive / negative and have a positive / negative numerical measure according as its defining rotation is in the counterclockwise / clockwise direction
- the absolute value of the measure of a rotary angle in degrees / radians may be determined by (the possibly repeated use of) the measurement of sectorial angles in degrees / radians
- there is also a unit of measure of rotary angles called turn = 360° = $2\pi^r$ = once around the (counter) clock

□ some nonnegative rotary angles
measured in degrees / radians / turns

$$\bullet 0^\circ = 0^r = \text{zero turns}$$

$$\bullet 90^\circ = \frac{\pi^r}{2} = \text{quarter - turn}$$

$$\bullet 180^\circ = \pi^r = \text{half - turn}$$

$$\bullet 270^\circ = \frac{3\pi^r}{2} = \text{three - quarter - turn}$$

$$\bullet 360^\circ = 2\pi^r = \text{one turn}$$

$$\bullet 720^\circ = 4\pi^r = \text{two turns}$$

$$\bullet 1080^\circ = 6\pi^r = \text{three turns}$$

etc

□ the measure in radians = the radian measure of radial angles

- by definition

the measure in radians = the radian measure of a radial angle

is

the numerical value

of the length s of the intersection M of the radial angle

and

the unit circle U

with center at the vertex of the radial angle

if the length of M exists;

if not

and

if M is Lebesgue measurable in dimension 1 on U ,

then the numerical value

of the 1 - dimensional Lebesgue measure of M

may be used as the measure of the radial angle;

note that the radial angle is subtended by M

□ the measure in steradians = the steradian measure of solid angles

- by definition

the measure in steradians = the steradian measure of a solid angle

is

the numerical value

of the area S of the intersection M of the solid angle

and

the unit sphere U

with center at the vertex of the solid angle

if the area of M exists;

if not

and

if M is Lebesgue measurable in dimension 2 on U ,

then the numerical value

of the 2 - dimensional Lebesgue measure of M

may be used as the measure of the solid angle;

note that the solid angle is subtended by M

□ notation for steradian measure

• the notation for steradian measure is

n steradians = n sr = n^{sr} wh $n \in \text{nonneg real nr}$

□ some examples of the steradian measure of solid angles

• one octant solid angle = $\frac{\pi^{\text{sr}}}{2}$

• one quarter – turn
dihedral solid angle = π^{sr}

• one flat solid angle = $2\pi^{\text{sr}}$

• one three - quarter - turn
dihedral solid angle = $3\pi^{\text{sr}}$

• all space solid angle = $4\pi^{\text{sr}}$

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□ two analogous theorems,
one in the plane
and
one in space

- let a circle of radius r be centered
at the vertex of a radial plane angle
with radian measure α
and let circle and angle intersect in a set of length s ;
then

$$s = r\alpha \quad \& \quad \alpha = \frac{s}{r}$$

- let a sphere of radius r be centered
at the vertex of a solid angle
with steradian measure α
and let sphere and angle intersect in a set of area S ;
then

$$S = r^2\alpha \quad \& \quad \alpha = \frac{S}{r^2}$$

□ two analogous corollaries
to the two preceding analogous theorems,
one in the plane
and
one in space

- an arc of length 1
on a circle of radius 1
subtends
a central plane angle of 1 radian

- a region of area 1
on a sphere of radius 1
subtends
a central solid angle of 1 steradian

□ measures of time

- by definition

measures of time include

1 day

= one mean solar day

= the (apparent) revolution period of the averaged Sun

1 day = 1 da = 1 d = 1^{da} = 1^d

= 24 hours = 24 hr = 24 h = 24^{hr} = 24^h

1 hour = 1 hr = 1 h = 1^{hr} = 1^h

= 60 minutes = 60 min = 60 m = 60^{min} = 60^m

1 minute = 1 min = 1 m = 1^{min} = 1^m

= 60 seconds = 60 sec = 60 s = 60^{sec} = 60^s

1 second = 1 sec = 1 s = 1^{sec} = 1^s = ca one heart beat

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- the basic relationship between the sexagesimal measure of time and the sexagesimal measure of angle; by definition

$$1 \text{ day} = 360^\circ$$

because

the averaged Sun makes exactly one (apparent) revolution in one mean solar day

whence

$$1 \text{ day of time} = 1^{\text{d}} = 360^\circ = 360 \text{ degrees of angle}$$

$$1 \text{ hour of time} = 1^{\text{h}} = 15^\circ = 15 \text{ degrees of angle}$$

$$1 \text{ minute of time} = 1^{\text{m}} = 15' = 15 \text{ minutes of angle}$$

$$1 \text{ second of time} = 1^{\text{s}} = 15'' = 15 \text{ seconds of angle}$$

□ comparing notation for time and for angle

- time

= A hours + B minutes + C seconds

= A hr B min C sec

= A h B m C s

= $A^{\text{hr}} B^{\text{min}} C^{\text{sec}}$

= $A^{\text{h}} B^{\text{m}} C^{\text{s}}$

- angle

= A degrees + B minutes + C seconds

= A deg B min C sec

= $A^{\circ} B' C''$

□ the standard equivalence
between angle measure & time measure

• angle to time

$$360^\circ = 24^{\text{h}}$$

$$270^\circ = 18^{\text{h}}$$

$$180^\circ = 12^{\text{h}}$$

$$90^\circ = 6^{\text{h}}$$

$$1^\circ = 4^{\text{m}}$$

$$1' = 4^{\text{s}}$$

$$1'' = \left(\frac{1}{15}\right)^{\text{s}}$$

• time to angle

$$24^{\text{h}} = 360^{\circ}$$

$$18^{\text{h}} = 270^{\circ}$$

$$12^{\text{h}} = 180^{\circ}$$

$$6^{\text{h}} = 90^{\circ}$$

$$1^{\text{h}} = 15^{\circ}$$

$$1^{\text{m}} = 15'$$

$$1^{\text{s}} = 15''$$

□ the seven special (= integer - hour) angles in quadrant I
into
degrees, radians, hours

$$\text{since } 1^{\text{h}} = 15^{\circ} = \frac{\pi^{\text{r}}}{12}$$

it follows that

$$\bullet 0^{\circ} = 0^{\text{r}} = 0^{\text{h}}$$

$$\bullet 15^{\circ} = \frac{\pi^{\text{r}}}{12} = 1^{\text{h}}$$

$$\bullet 30^{\circ} = \frac{\pi^{\text{r}}}{6} = 2^{\text{h}}$$

$$\bullet 45^{\circ} = \frac{\pi^{\text{r}}}{4} = 3^{\text{h}}$$

$$\bullet 60^{\circ} = \frac{\pi^{\text{r}}}{3} = 4^{\text{h}}$$

$$\bullet 75^{\circ} = \frac{5\pi^{\text{r}}}{12} = 5^{\text{h}}$$

$$\bullet 90^{\circ} = \frac{\pi^{\text{r}}}{2} = 6^{\text{h}}$$

□ an illustration of esthetics
as a guiding principle in mathematics

- a pretty formula

defines radian measure of a sectorial angle;

think of a given circle

with a given central angle

intercepting a subtending arc on the circle;

think of the associated numbers

viz

the length of the radius = r

the length of the subtending circle arc = s

the measure of the central angle = α (to be determined)

and note the alphabetic choices of initial letters of words;

then the following formula holds

$$s = r \alpha$$

if and only if

$$\alpha = \frac{s}{r}$$

which is the definition

of the radian measure of the central angle;

no other definition of angle measure will do
to make the desired formula hold;

eg

if the angle α were measured in degrees,
then the formula would become

$$s = \frac{\pi}{180} r \alpha$$

which is not so pretty

nor so simple nor so efficient nor so theoretically useful;

one can say that radian measure of angles

is natural and inevitable

while degree measure of angles

is an historical accident

altho it is now well - entrenched in our lives

and we have to make the best of it

(but it is not too bad at that)

□ historical comments

- we have the ancient Babylonians to thank for our present use of sexagesimal (= base 60) numeration in the measure of angle/arc/time which we inherited from them;
ca 2000 BCE the Babylonians in Mesopotamia, between the Tigris & Euphrates rivers in the Middle East, began to use a number system based on 60; they likely chose base 60 because of the relatively large number of factors of 60 which has the effect of producing lots of easily written fractions
- the ancient Babylonians & Greeks divided up the lighter day time into 12 equal parts & also the darker night time into 12 equal parts; 12 was likely chosen because 12 has many factors & 12 is still relatively small & 12 is also itself a factor of 60

- it is an historical accident that the degree of angle was chosen so that there are 360 degrees in a round angle; it was likely caused by taking the angle of an equilateral triangle viz 60 degrees as the unit of angle and then using the base 60 numeration system so that a degree is recognized as one-sixtieth of an angle of an equilateral triangle

- ca 150 CE

Claudius Ptolemy (Latin: Ptolemaeus) of Alexandria

(ca 90 - 168 CE, Egyptian;

astronomer, geographer, mathematician)

used characters on numbers with sexagesimal fractions

that resemble our present-day characters for

degree, minute, second of angle/arc

- in the 16th century

the characters

$^{\circ}$, $^{\prime}$, $^{\prime\prime}$, $^{\prime\prime\prime}$, iv , etc

(the first three are our familiar ones)

began to be used

as righthand superscripts

denoting

degrees, minutes, seconds, thirds, fourths, etc

in sexagesimal numeration

- the above symbols may be simply designations of

0, 1, 2, 3, 4, etc

which with negative signs are the exponents of 60

in a number given in units of degrees

with the fractional part written to the base 60

□ etymology of words
for the measures of angle/arc/time

- degree

from

degradus (Latin) = degree

from

de (Latin) = down

+

gradus (Latin) = grade, step

- hour

from

hora (Latin) = hour

from

ὥρα (Greek) = hour

- minute

from

minuta (Latin) = small

from

pars minuta prima (Latin) = first small part

- second

from

secunda (Latin) = second

from

pars minuta secunda (Latin) = second small part

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- radian
 from
radius (English)
 from
radius (Latin) = spoke of a wheel

- steradian
 from
ste- = abbreviation of
stereo- (English) = solid
+
radian (English)

- sexagesimal = relating to the number sixty
 from
sexigesimus (Latin) = sixtieth
 from
sexaginta (Latin) = sixty

- clockwise = rotating like the hands of a clock
from
clock (English)
+
-wise (English) = in the manner of

- counterclockwise = rotating contrary to the hands of a clock
from
counter- (English) = opposite
+
clockwise (English)

- the word 'radian' first appeared in print in 1879;

'radian' comes from

the Latin-English word

radius minus -us plus -an;

the Latin word 'radius'

means many things

viz

beam of light

bone in human forearm

kind of long olive

measuring rod

radius of a circle

ray

rod

spoke of a wheel

staff

stake

weaving shuttle

- the word 'steradian' first appeared in print in 1881;

the prefix 'ste-' comes from

the English prefix 'stereo-' = solid

which comes from the Greek word

στερεος = solid

- a wild guess:

radius + angle

= radi + an

= radian